

Evolution of pavement diagnosis to the next generation

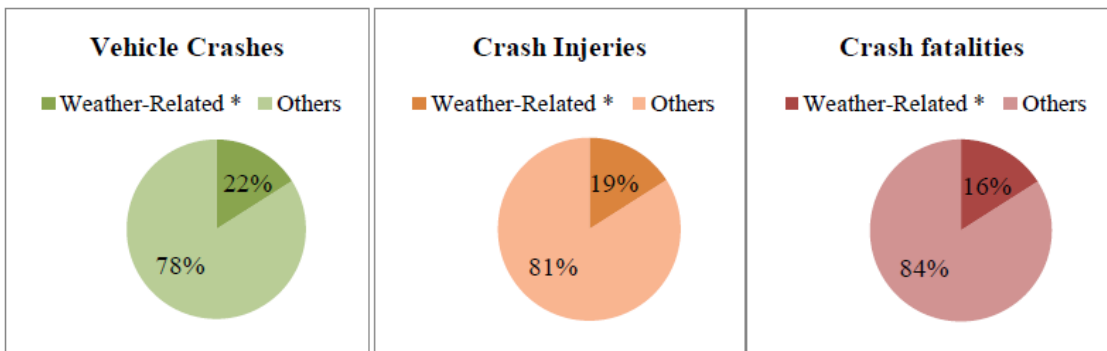
# Analysis of the effect of road surface conditions and rutting on vehicle dynamics using CARSIM

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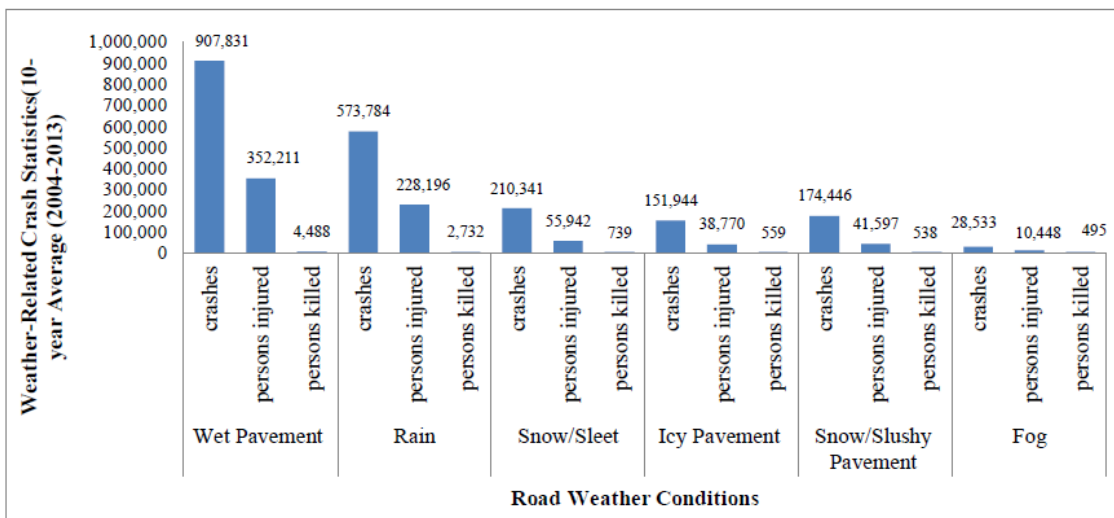
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# Introduction

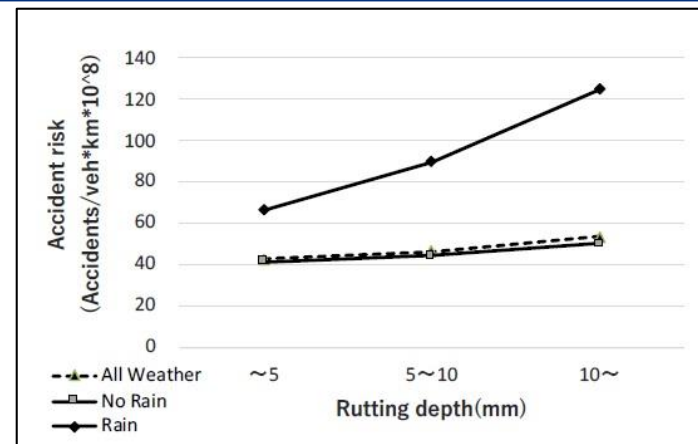


Note: "Weather-Related" crashes are those that occur in the presence of adverse weather and/or slick pavement conditions



## Weather-Related Crash Statistics (10-year), USA

Kordani et. al. 2018, <http://dx.doi.org/10.28991/cej-030967>



- ◆ Accident ratio related to bad weather and/or road surface conditions is high.

## Rutting depth vs. accident risk in Japan

Tsubota et al., 2019, [https://doi.org/10.2208/jscejipm.75.I\\_1081](https://doi.org/10.2208/jscejipm.75.I_1081)

- ◆ Lane change, obstacle avoidance in rutting + wet, snow or icy road surfaces => vehicle spinning and uncontrollable driving path => may cause serious accidents.
- ◆ Understanding vehicle dynamic behaviors in such conditions is important to provide proper road design, maintenance and repair to ensure safety driving.

This study used CARSIM, a vehicle dynamic simulation software, to model and analyze the yaw motion of a normal car and a light truck in a double-lane-change (DLC) maneuver under different road surface conditions.

## Considered conditions

### I. Rutting

- Single rut
- Dual rut

### II. Road surface conditions

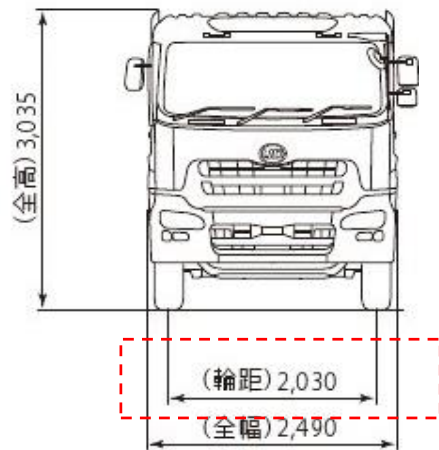
- Pavement: Dry, Wet, Snow and Icy conditions

### III. Vehicle

- Normal car
- Light truck

# Simulated single and dual ruts

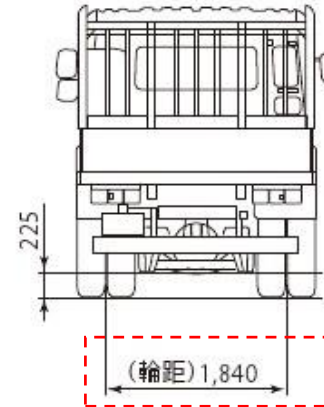
Rut widths were based on the configuration of big box trucks



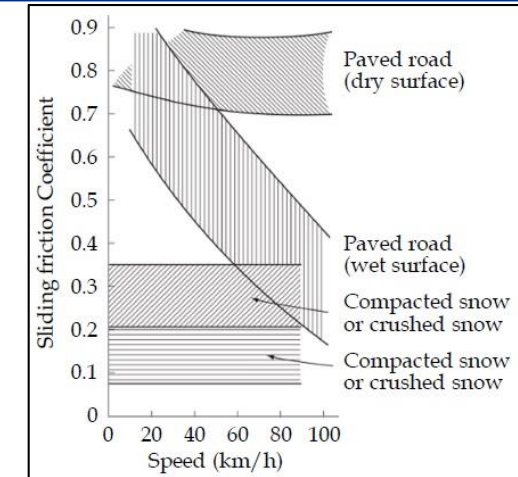
Single rut, 2030 mm



Wheel width  
max = 30 cm



Dual rut, 1840 mm

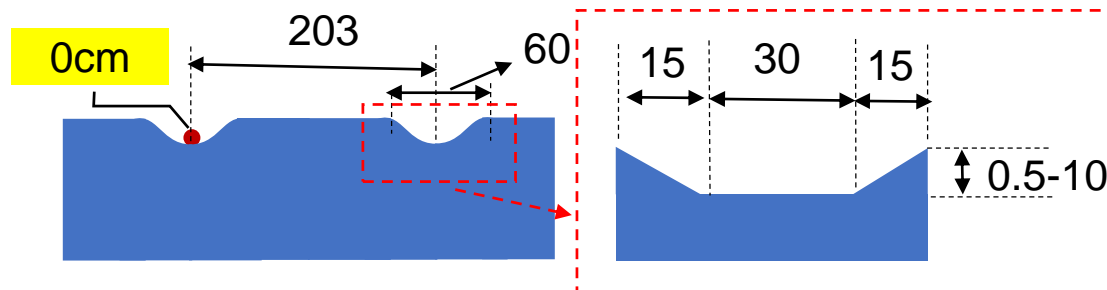


Friction coefficients

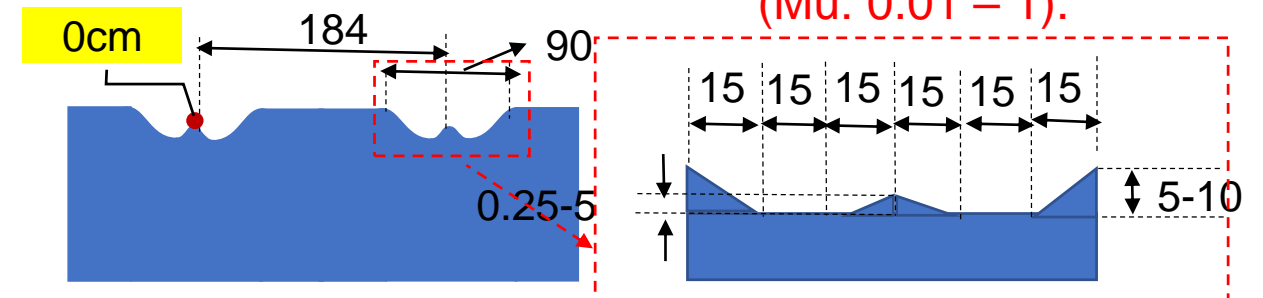
Kageyama et. al. 2021

<https://doi.org/10.3390/app12010018>

( $\mu$ : 0.01 – 1).



Single rut (cm), Wheel position (●)



Dual rut (cm), Wheel position (●)

# Vehicles and driving paths

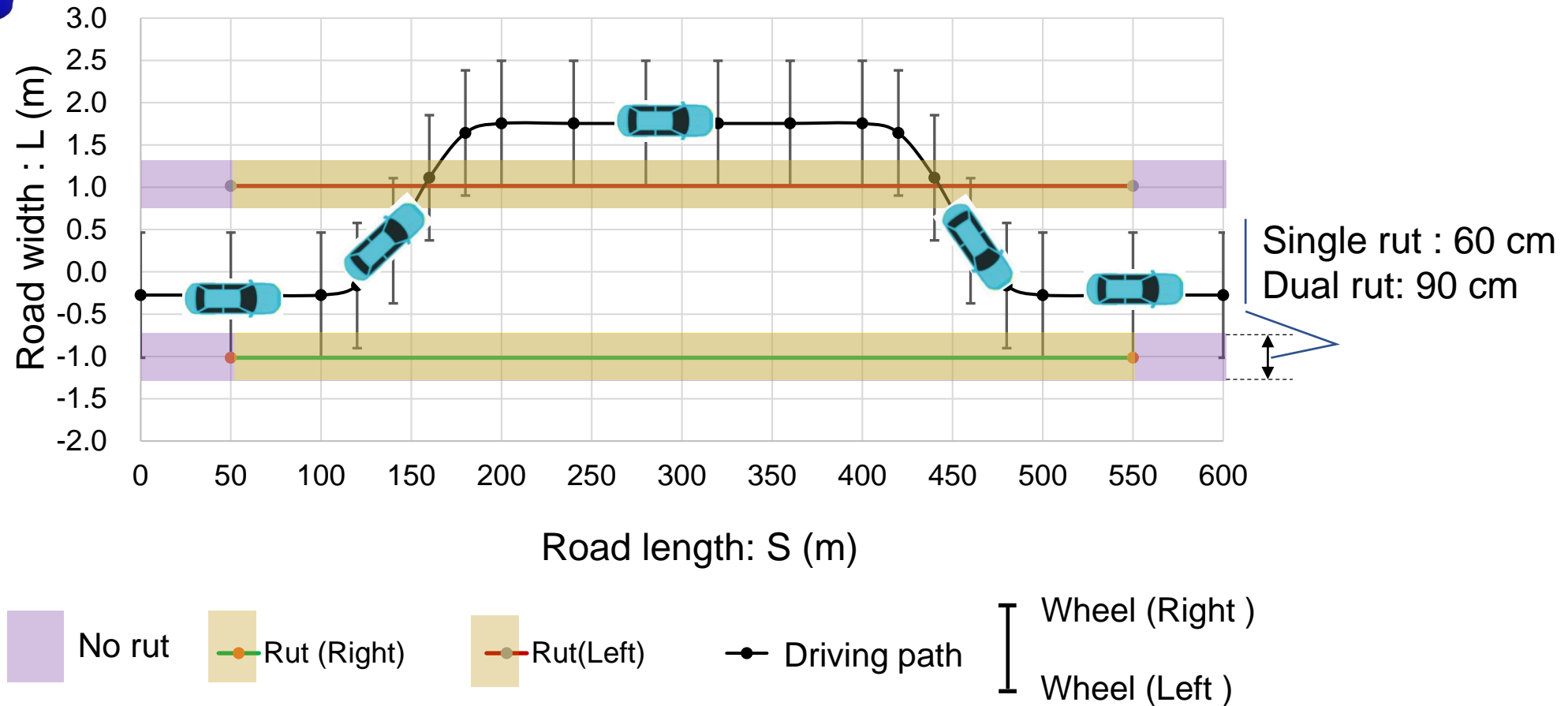


Normal car

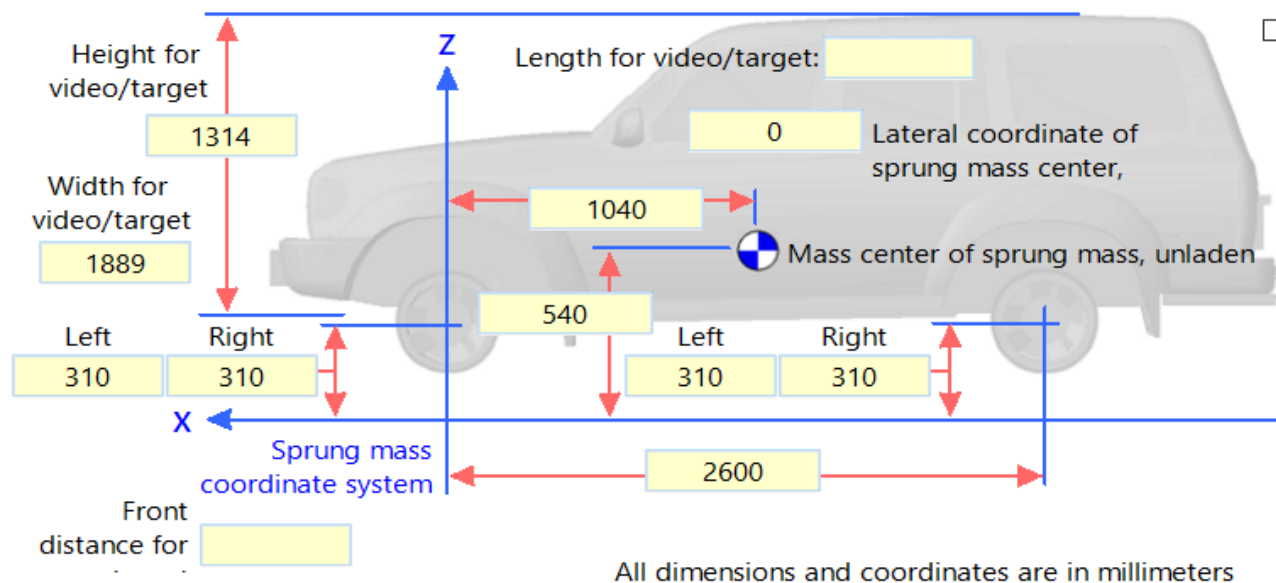


Light Truck

Driving path (m), Speed 60 km/h



# Normal car



Based on B-Class Hatchback (CARSIM)

The inertia properties below are all for the sprung mass, unladen

Sprung mass: 1110 kg

☐ Edit radii of gyration

Roll inertia: 440.6 kg-m<sup>2</sup>

Rx: 0.630 m

Pitch inertia: 1343.1 kg-m<sup>2</sup>

Ry: 1.100 m

Yaw inertia: 1343.1 kg-m<sup>2</sup>

Rz: 1.100 m

Product (I<sub>xy</sub>): 0 kg-m<sup>2</sup>

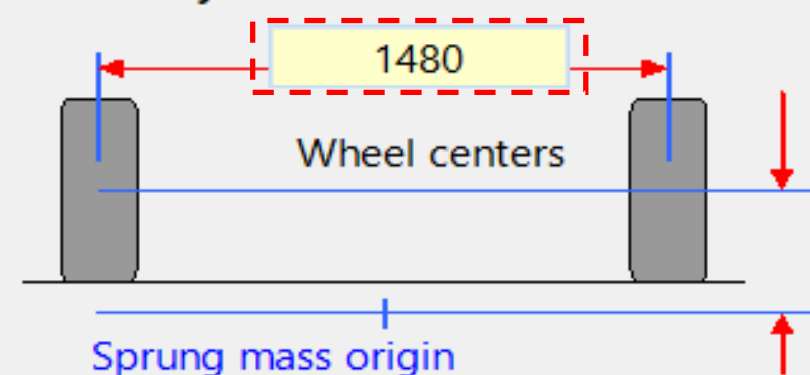
Inertia and radius of gyration are related by the equation:  $I = M \cdot R^2$

Product (I<sub>xz</sub>): 0 kg-m<sup>2</sup>

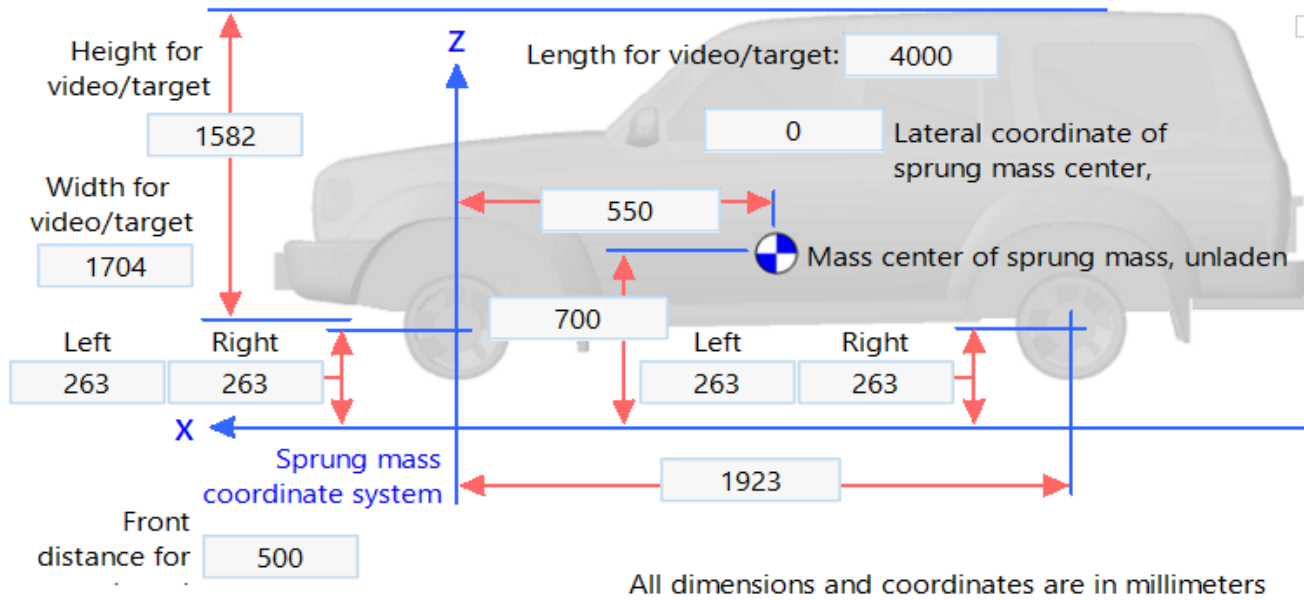
Product (I<sub>yz</sub>): 0 kg-m<sup>2</sup>

Radii must be specified with numbers; formulas are not supported

## Geometry



# Light truck



Based on Utility compact Truck (CARSIM)

The inertia properties below are all for the sprung mass, unladen

Adv

Sprung mass: 600 kg

☐ Edit radii of gyration

Roll inertia: 384 kg-m<sup>2</sup>

Rx: 0.800 m

Pitch inertia: 624 kg-m<sup>2</sup>

Ry: 1.020 m

Yaw inertia: 686 kg-m<sup>2</sup>

Rz: 1.069 m

Product (I<sub>xy</sub>): 0 kg-m<sup>2</sup>

Inertia and radius of gyration are related by the equation:  $I = M \cdot R^2$

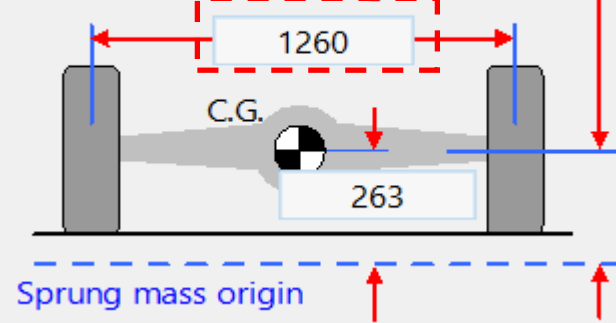
Product (I<sub>xz</sub>): 0 kg-m<sup>2</sup>

Product (I<sub>yz</sub>): 0 kg-m<sup>2</sup>

Radii must be specified with numbers; formulas are not supported

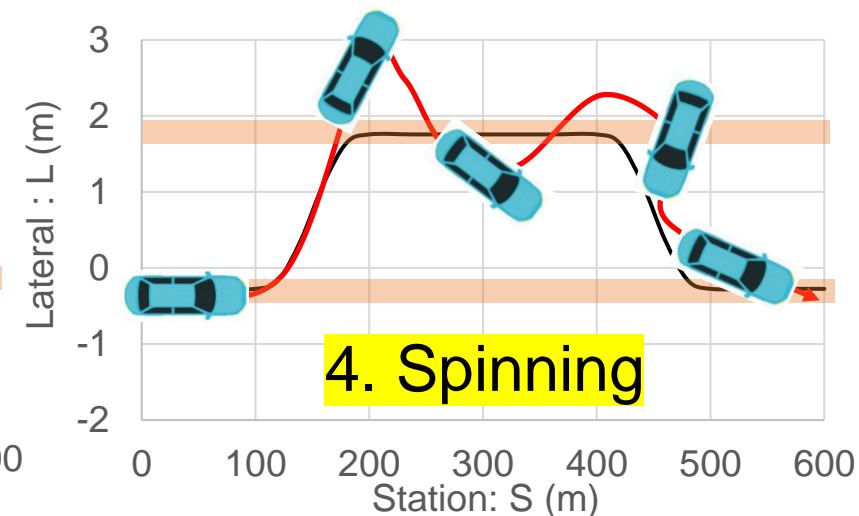
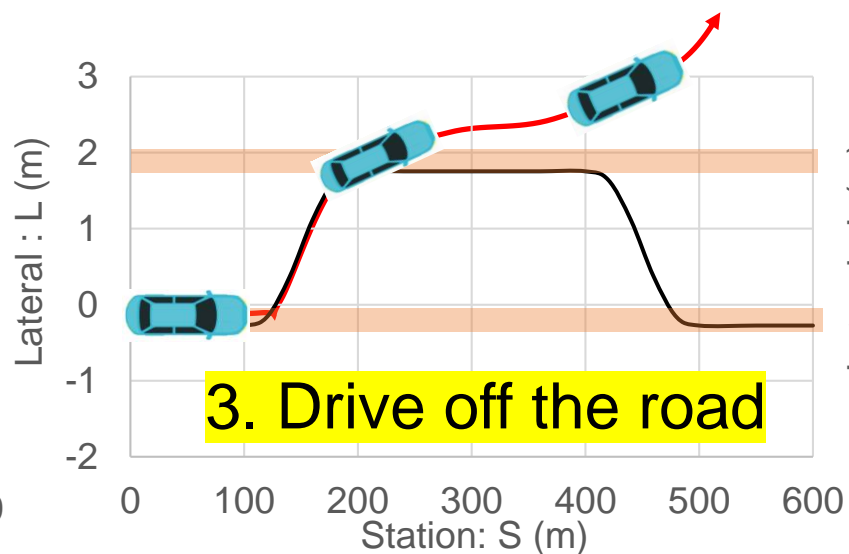
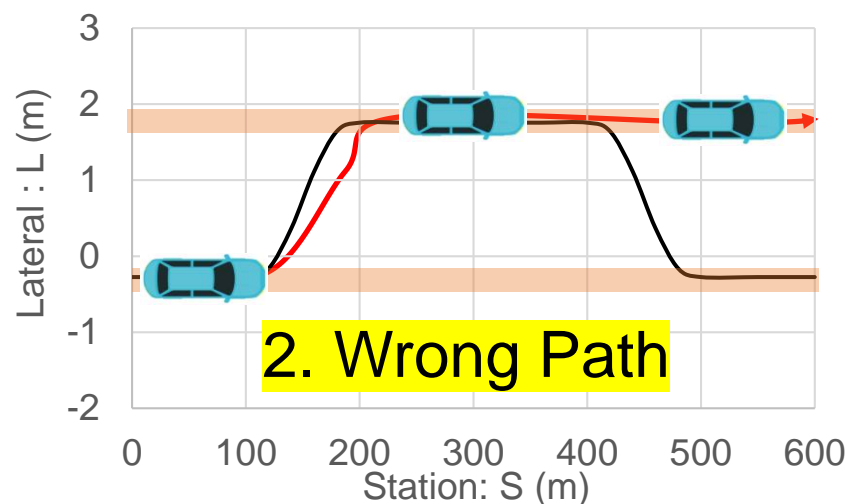
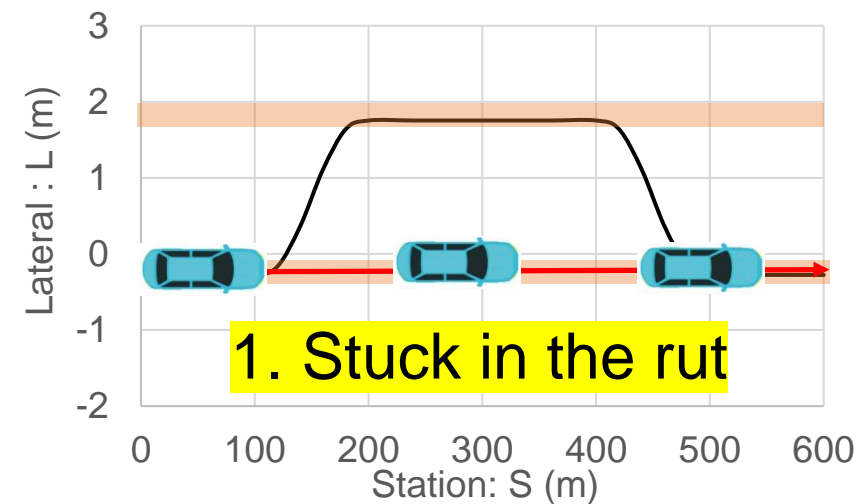
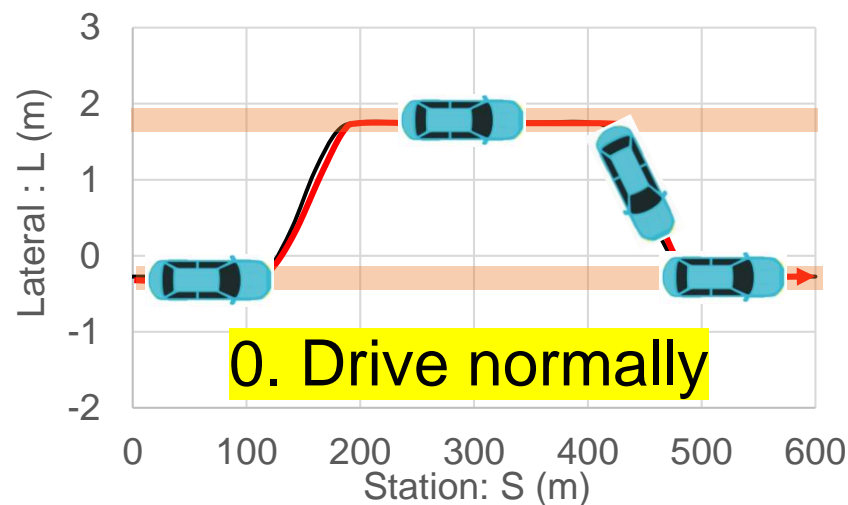
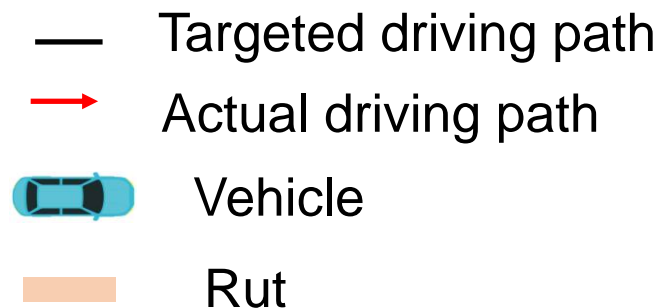
## Geometry

☐ Set wheel center height here





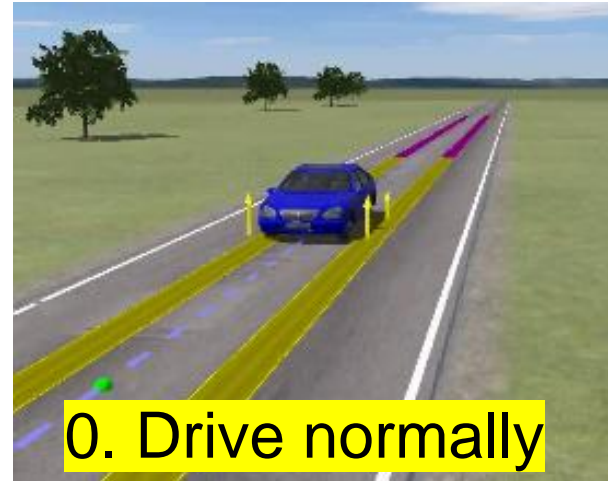
# Driving behaviors



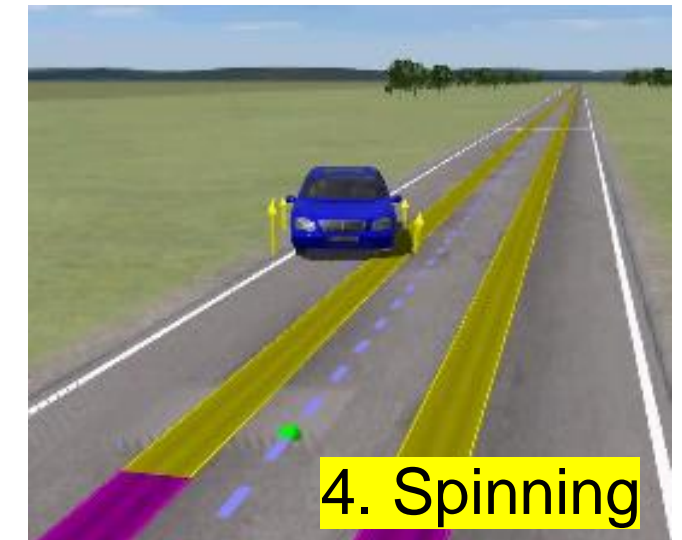
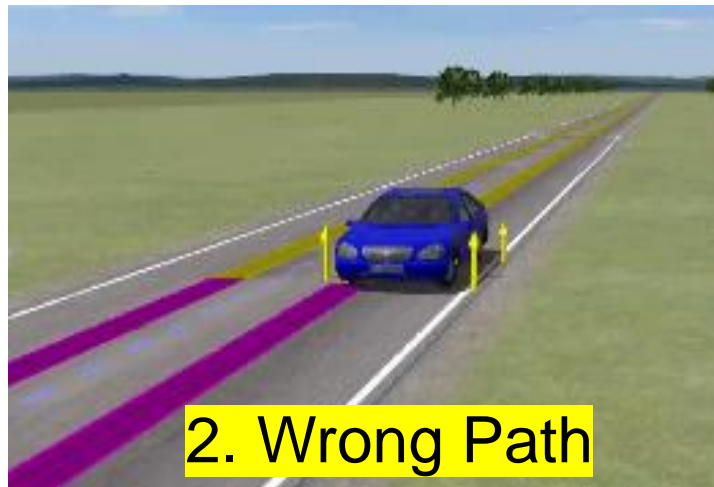


# Driving behaviors

- 0. Drive normally
- 1. Stuck in the rut
- 2. Wrong path
- 3. Drive off the road
- 4 Spinning

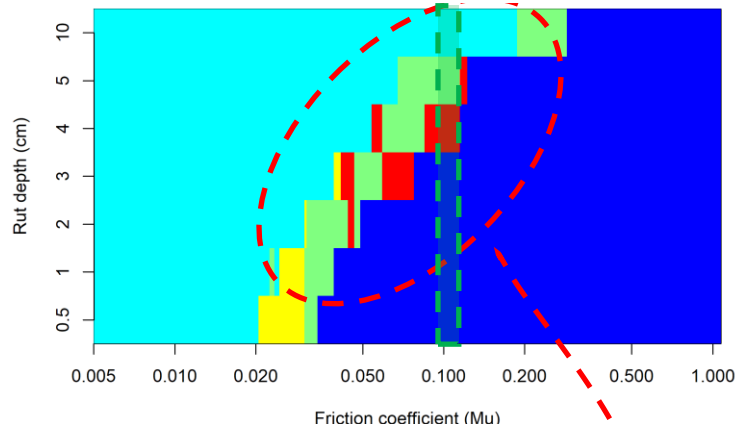


Wheel positions

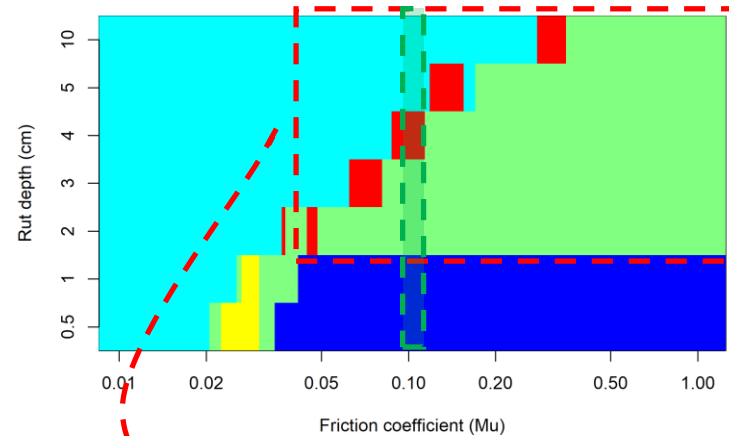


# Vehicle behavior based on rut depths and road surface types

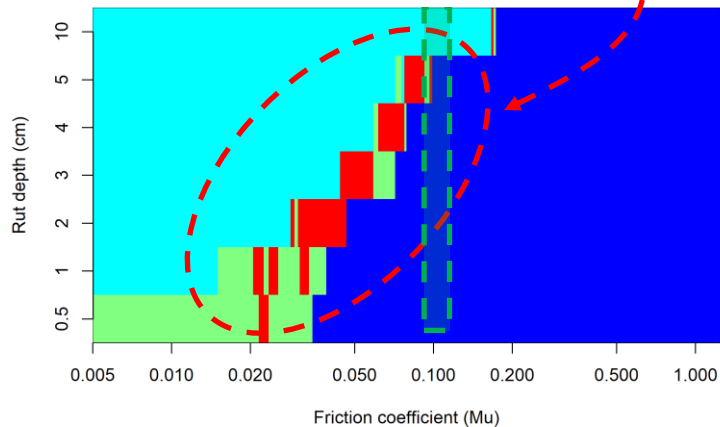
Normal car, single rut



Normal car, dual rut



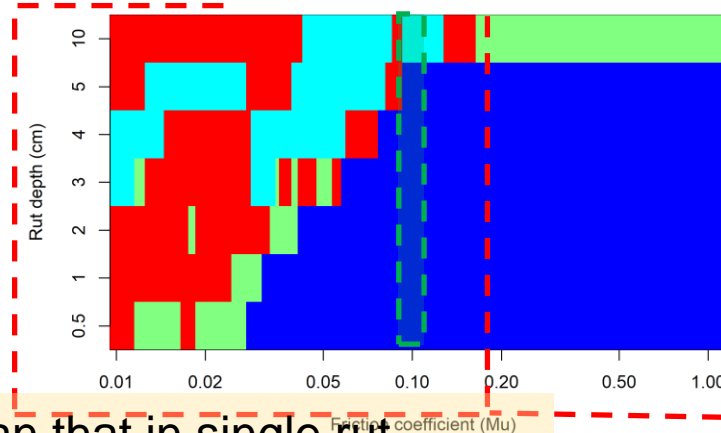
Light truck, single rut



More spin in light truck

$\mu < 0.4 \Rightarrow$  risky

Light truck, dual rut



Unstable driving

Cannot drive on the targeted path most of time  $\Rightarrow$  unstable driving

Spin on icy road

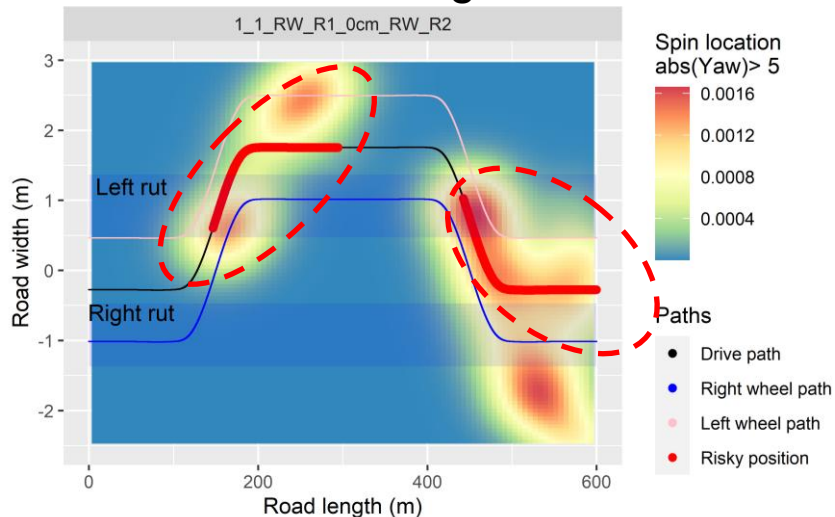
High risk of spinning on icy road

- Travelling in dual rut is more dangerous than that in single rut
- Light truck is unsafe when travelling on icy road

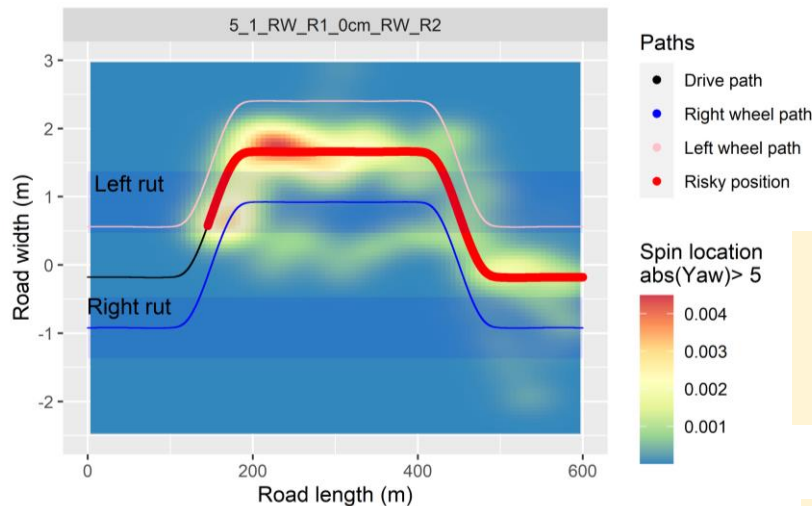
With  $\mu > 0.1$ , required RD  $< 1$  cm  $\Rightarrow$  safety

# Danger location with Yaw angle > 5

## Normal car, single rut



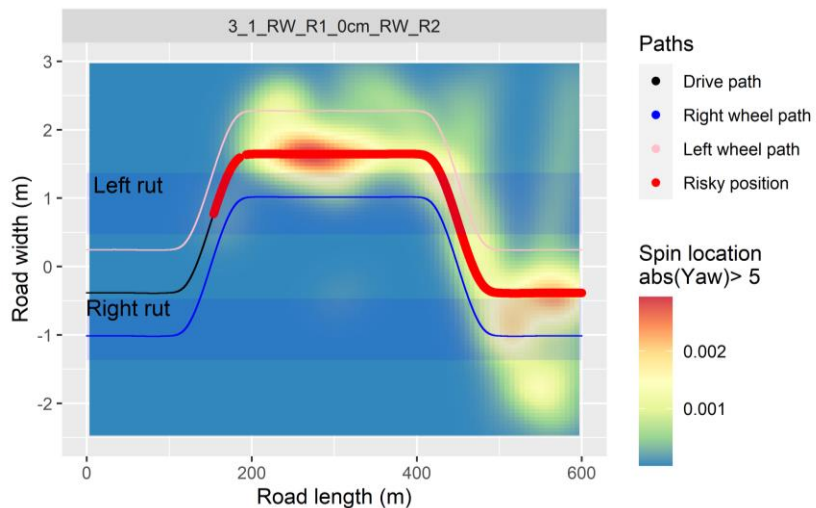
## Normal car, dual rut



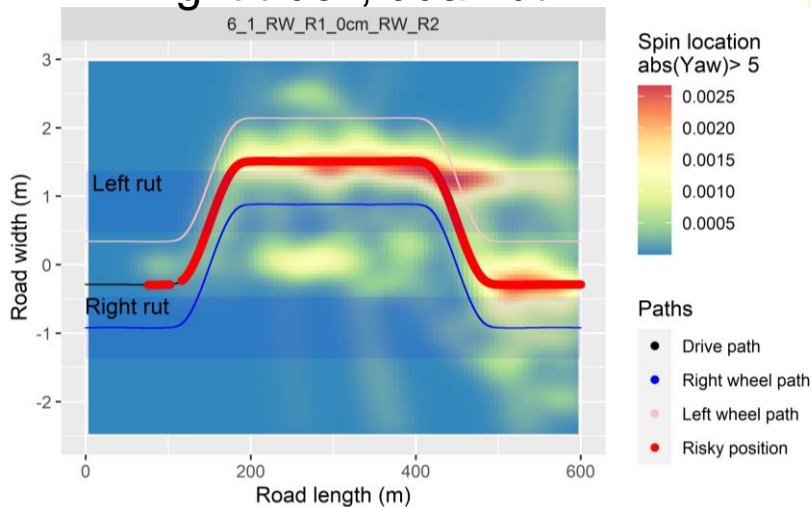
Mu 0.01-1, rut depth: 0.5-10 cm

- Normal car
- Spin mainly occurred at turning points on a single rut road

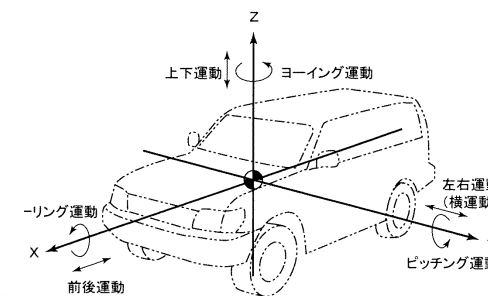
## Light truck, single rut



## Light truck, dual rut



- Large spin area in a dual rut road

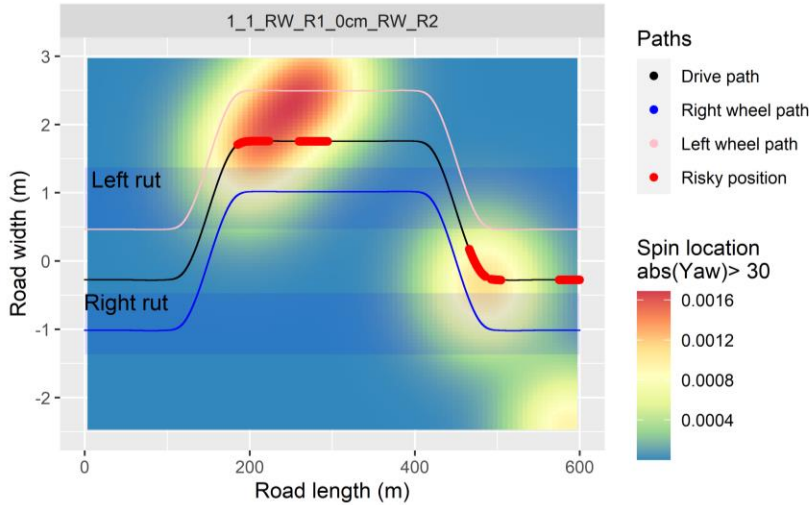


<https://www.webcartop.jp/2016/10/52015/>

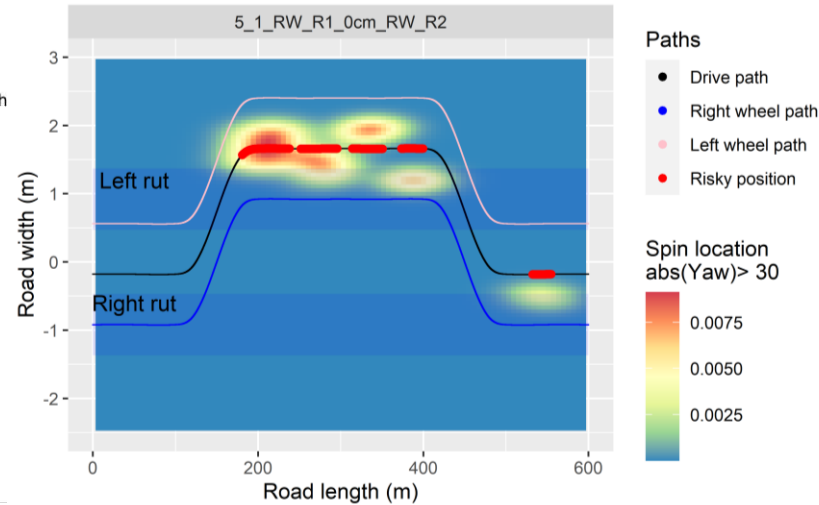


# Danger location with Yaw angle > 30

Normal car, single rut



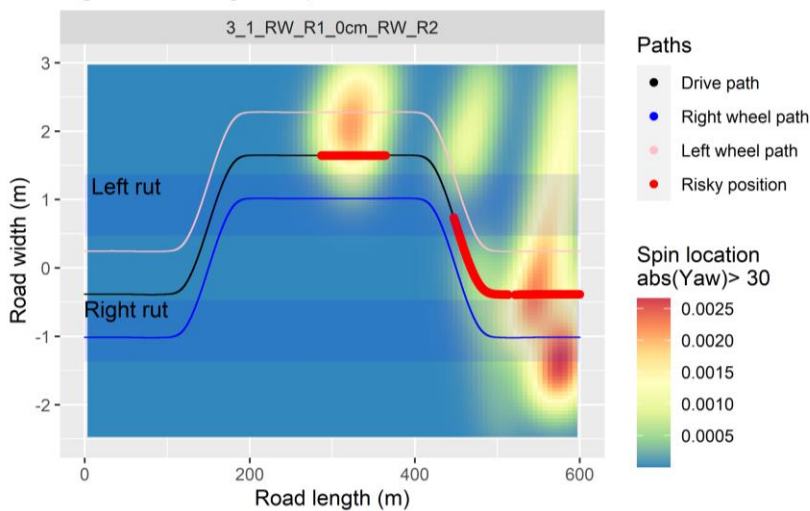
Normal car, dual rut



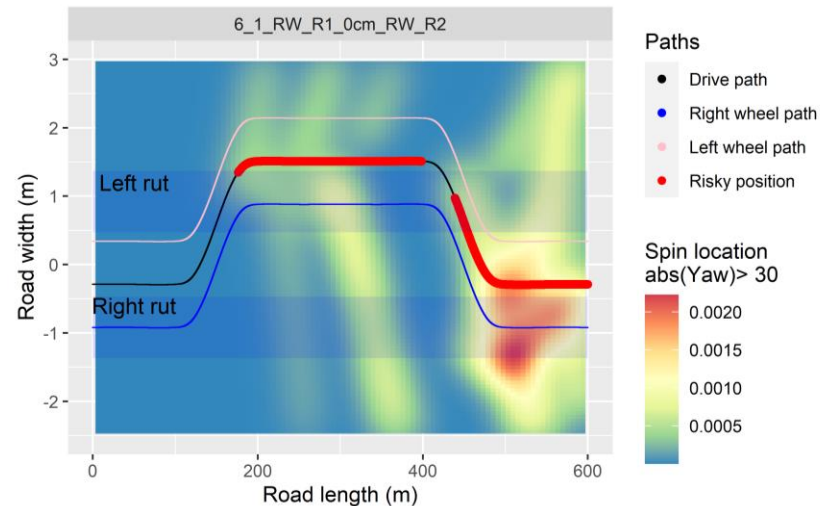
Mu 0.01-1, rut depth: 0.5-10 cm

- Normal car:  
High yaw angle mainly occurred when the car crossed the left rut

Light truck, single rut



Light truck, dual rut



- Light truck  
High yaw angle mainly occurred when the truck returned to the right rut.

# Conclusions

- ❑ Wrong path driving mainly occurred at  $\mu < 0.4$ , which was likely in icy, snow or wet road surface condition.
- ❑ Driving in dual rut roads was more dangerous than that in single rut roads.
- ❑ The light truck had a higher risk of spinning on icy road surfaces than the normal car.
- ❑ Spinning mainly occurred at turning points for the normal car while it could happen at any positions in a driving path for the light truck during DLC maneuvers.
- ❑ The deeper RD caused a higher risk of spinning and required a higher  $\mu$  to ensure safe driving.
- ❑ In a typical icy road condition  $\mu = 0.1$ ,  $RD < 1$  cm is recommended for safe driving.

***Thank you for your attention***